

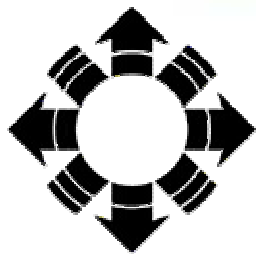
HEV Control Strategy for Real-Time Optimization of Fuel Economy and Emissions

Valerie H. Johnson

Co-authors: Keith B. Wipke, David J. Rausen

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NREL

National Renewable Energy Laboratory





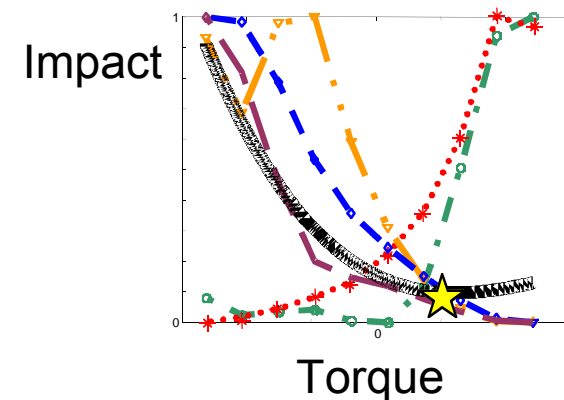
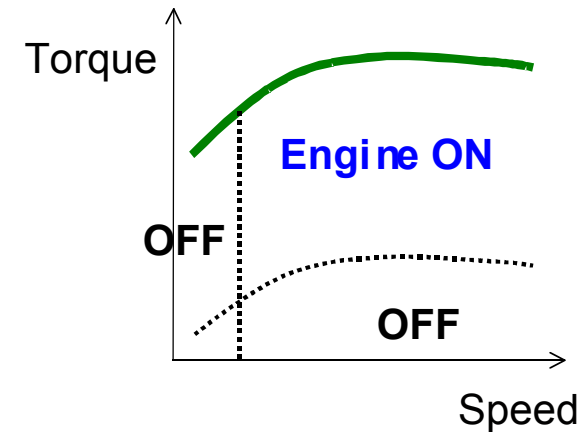
Outline

- Motivation and Introduction
- Guiding Concepts in Real-Time Control Strategy (RTCS)
- RTCS Concepts Explained
- Simulation Results
- Summary of RTCS
- Conclusions and Future Work



Motivation

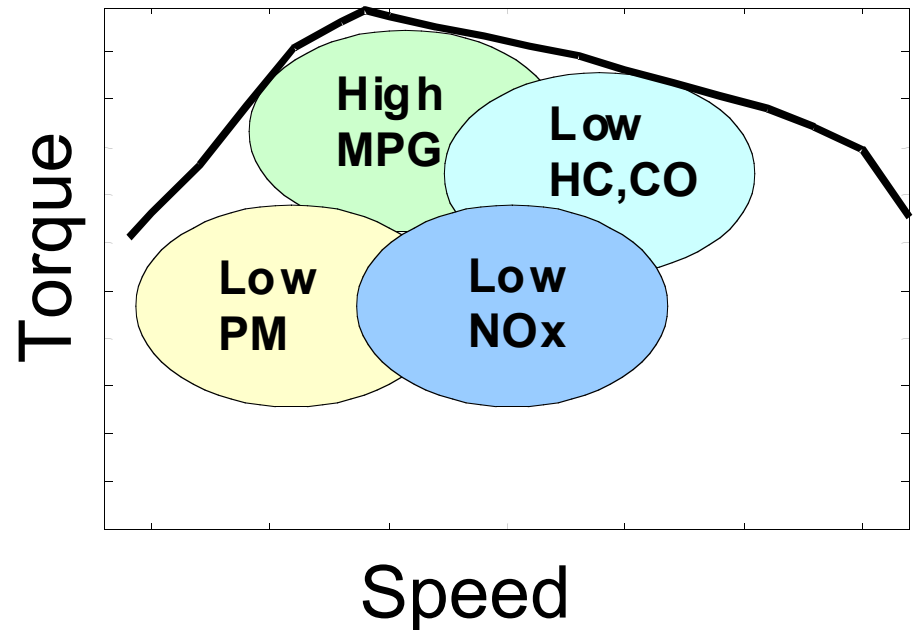
- Background: Parallel control strategies focus on **energy use**
 - Electric assist, motor used:
 - startup
 - low speeds, low torques
 - additional torque
 - Prius, Insight
- Goal of RTCS: Consider both **fuel economy** and **emissions**





Introduction

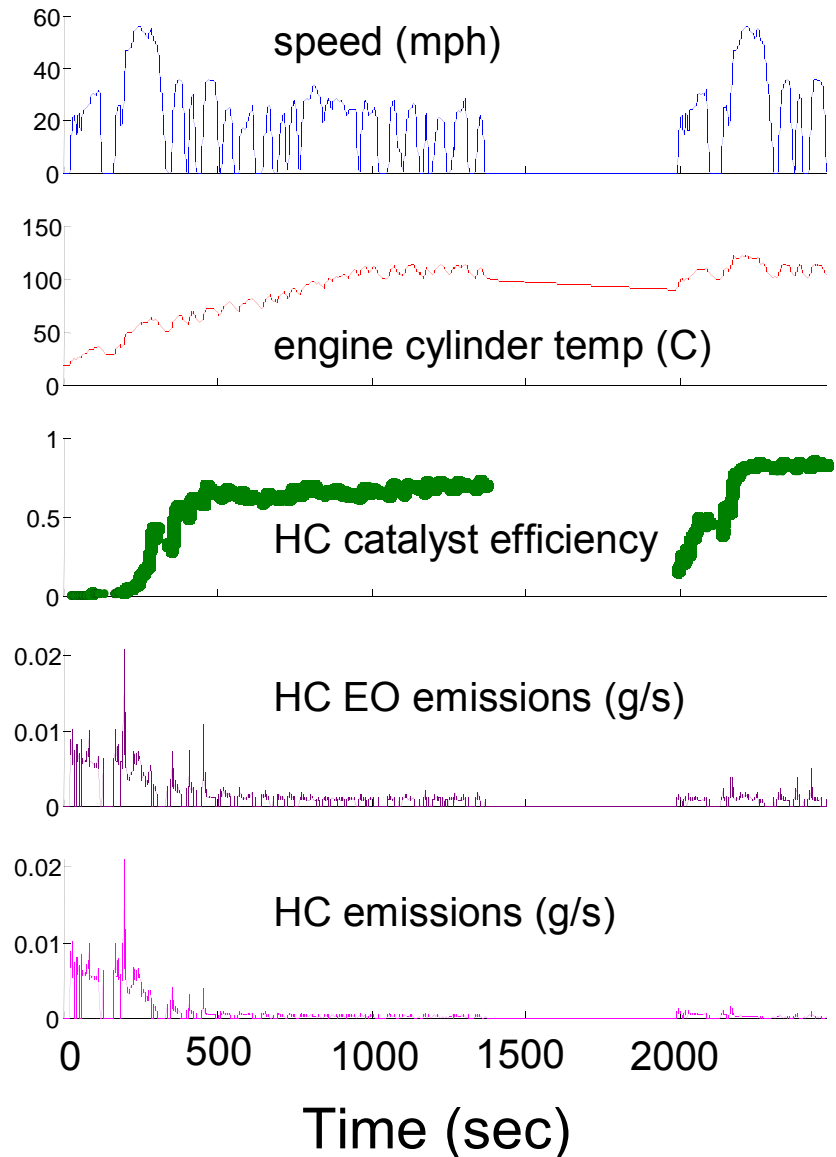
- **Tradeoffs** exist between optimum operating points for ICE fuel efficiency & emissions
- Must account for the energy used by the **electric side** of the hybrid





Introduction

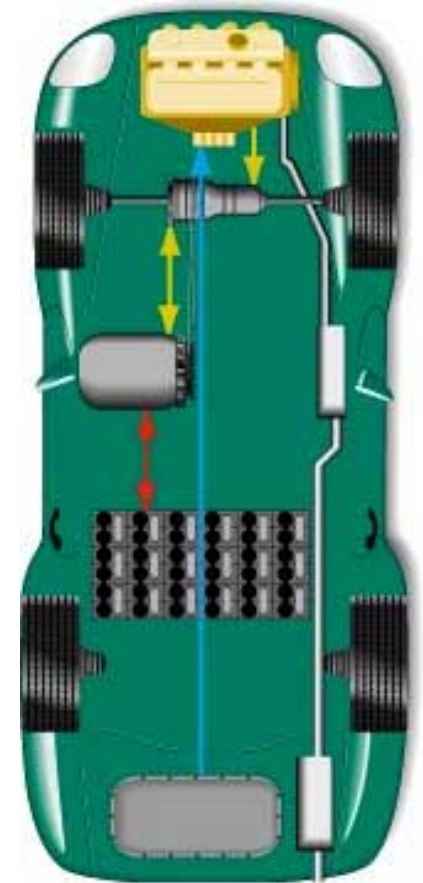
- Emissions and fuel use **vary with temperature** of engine, catalyst
 - 25-55% emissions when $T_{\text{engine}} < 95^{\circ}\text{C}$
- RTCS can **shift emphasis**
 - cold->emissions
 - hot->fuel economy





Guiding Concepts in Real Time Control Strategy (RTCS)

- **Entire vehicle** optimization
 - Includes instantaneous efficiencies of engine, exhaust removal, motor, and batteries
- **Real Time** Optimization of operating points
 - Includes temperature effects
- Amount of **free regenerative energy** calculated as the vehicle drives
 - Smoothing window in time





Guiding Concepts in RTCS, cont.

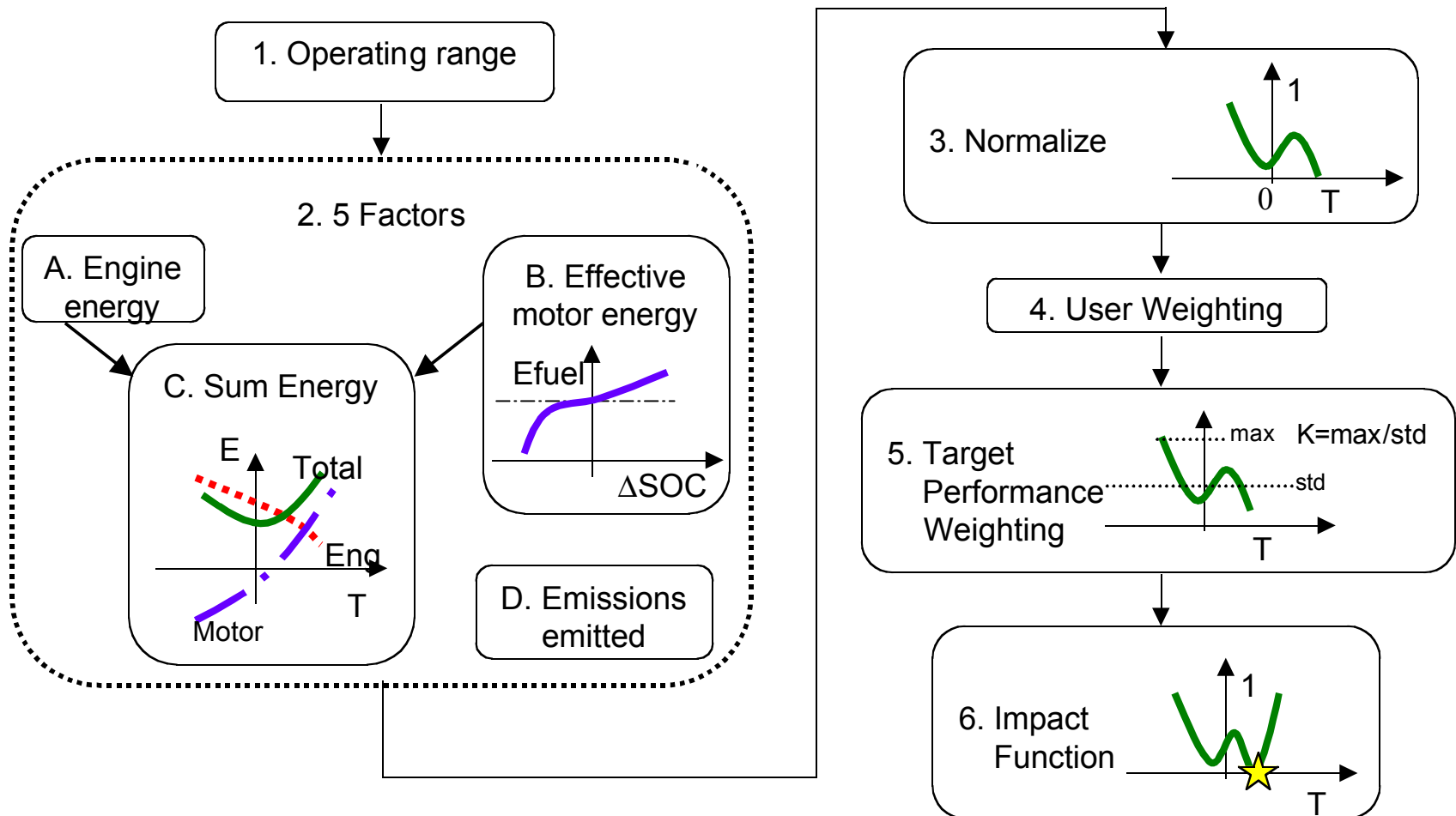
- **User-definable** targets for fuel economy and emissions
- **Entire range** of possible motor-engine torque combinations used
 - Optimums determined at each second
- Performance is weighted sum of instantaneous mpg and g/mi by **minimizing Impact Function**

Metric	Value	Unit
<i>Energy</i>	80	mpgge
<i>HC</i>	0.125	grams/mile
<i>CO</i>	1.7	grams/mile
<i>NOx</i>	0.07	grams/mile
<i>PM</i>	0.08	grams/mile

Based on PNGV goals and Tier 2 levels proposed (see www.epa.gov/oms/tr2home)

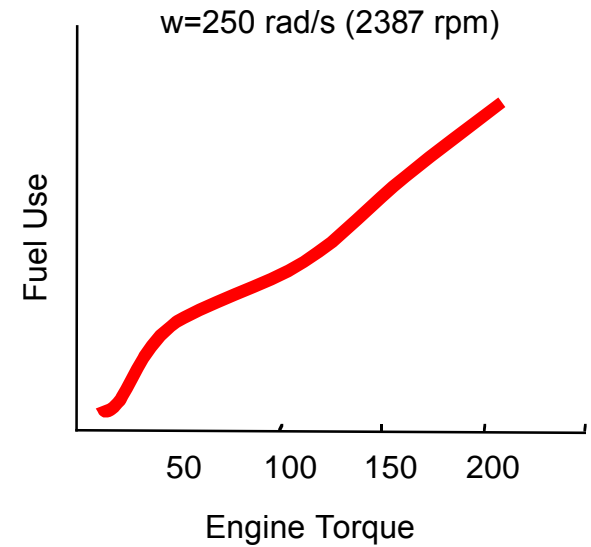
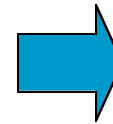
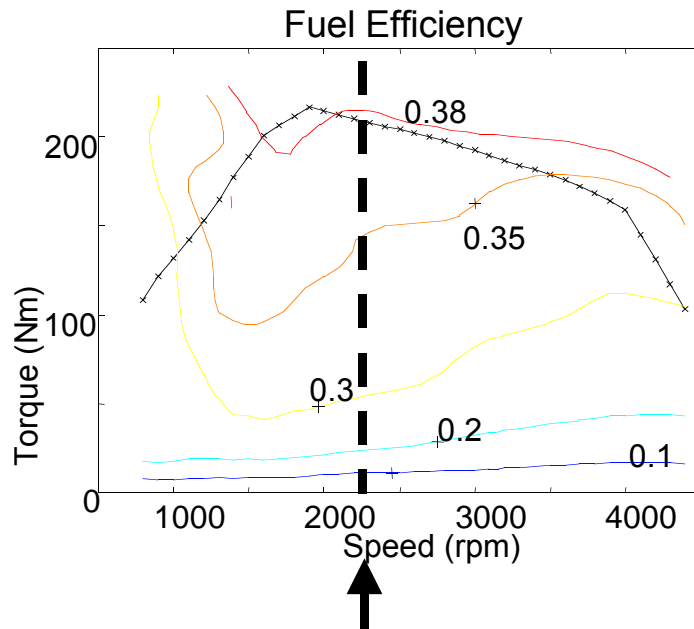
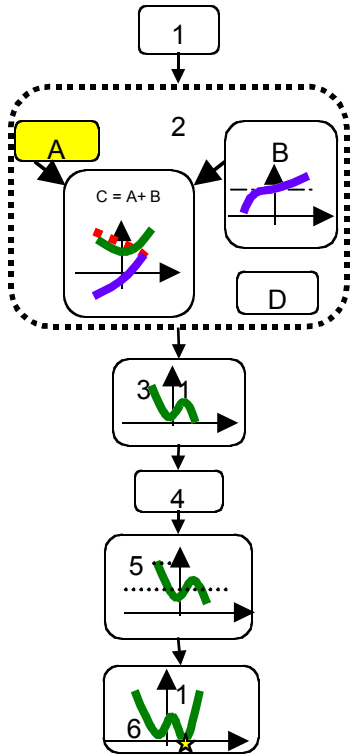


RTCS Flow Chart





Fuel Energy vs. Torque

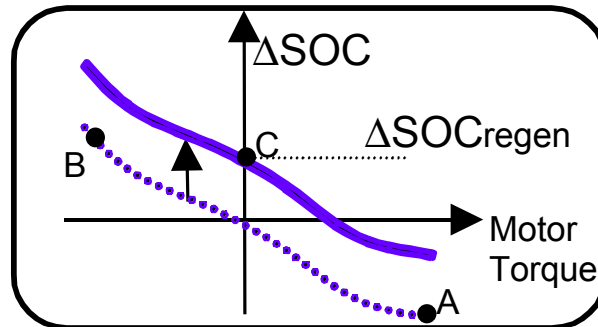
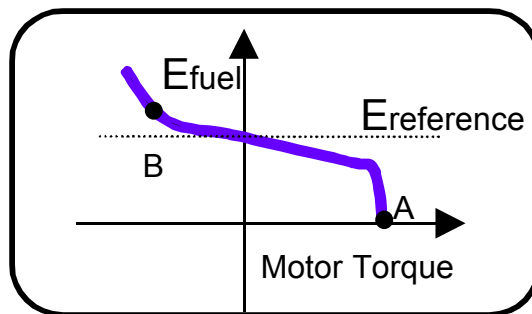
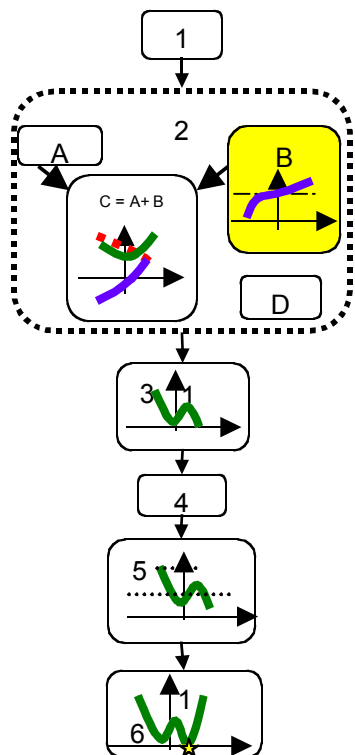


Real Time Control Strategy

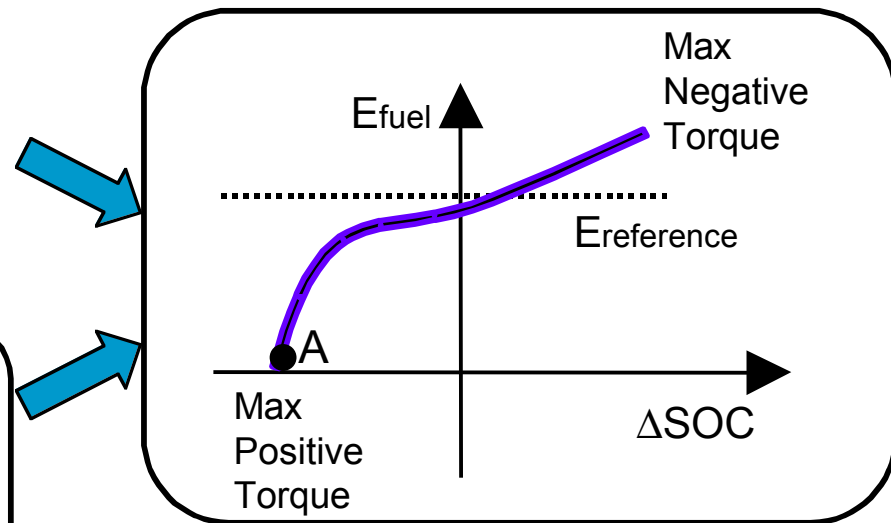


Effective Motor/Battery Energy

- Battery energy used is converted to an equivalent fuel
 - “Replacement-Energy” assuming similar operating conditions in the future



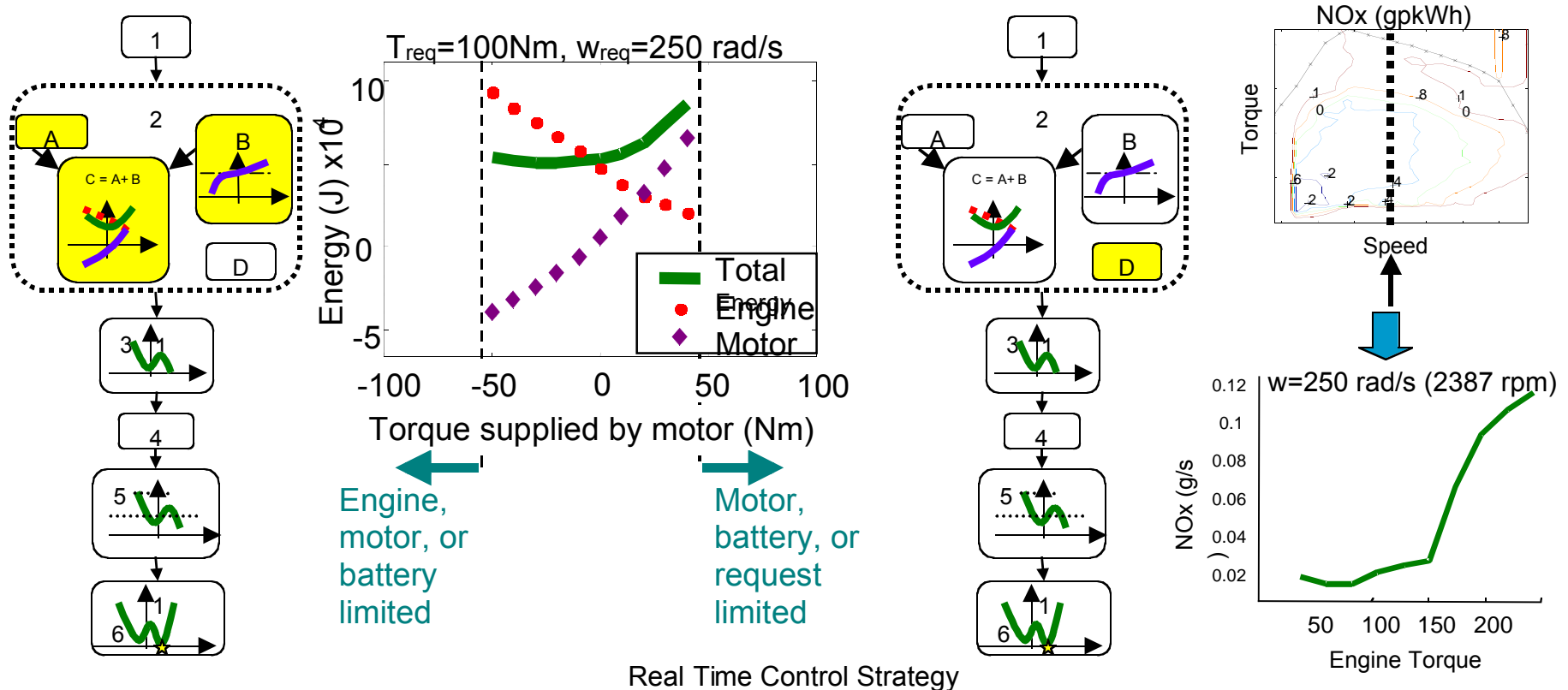
Real Time Control Strategy





Energy & Emissions vs. Torque

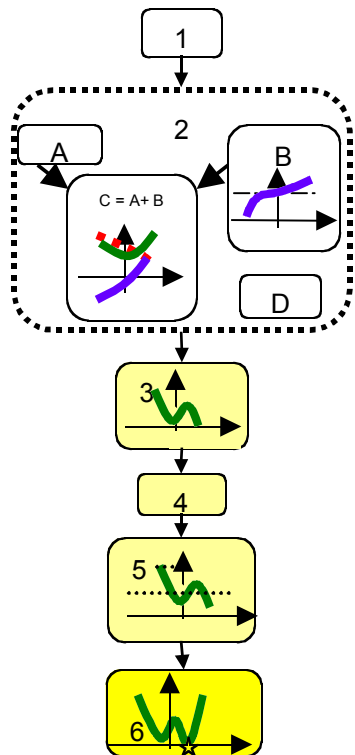
- Electrical Energy, Fuel Energy and Emissions found as they vary with torque distributions



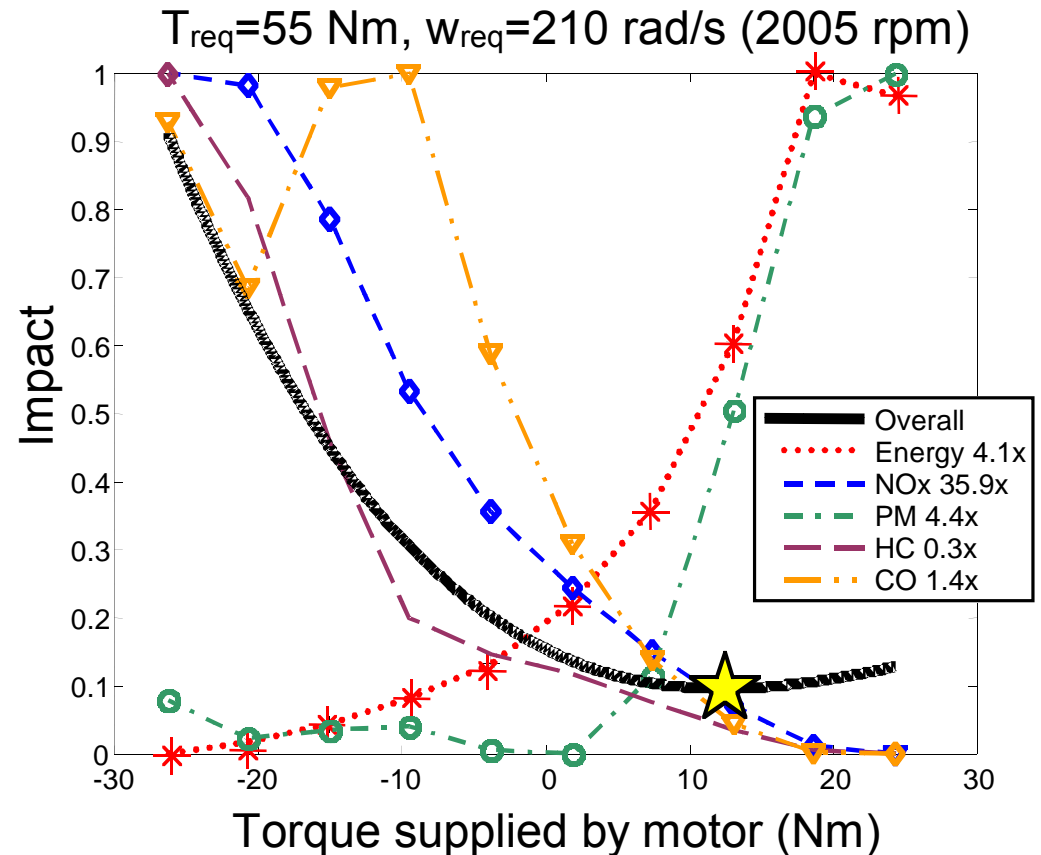


Impact Function

- 5 competing metrics are combined into a single **Impact Function**



- Normalization
- Target performance weighting
- Minimize





Simulation Description

- Vehicle Simulated with ADVISOR
- Cycles:
 - FTP
 - HWFET
 - US06
 - J-1015
 - NEDC



<i>Parameter</i>	<i>Value</i>	<i>Details</i>
Engine	42 kW	CIDI, scaled from 67kW VW 1.9L
Motor	32 kW	AC, scaled from Westinghouse 75 kW
Batteries	Twelve 18 Ah	spiral-wound lead acid
Mass	1028 kg	(2266 lbs)
Cd	0.2	
Area	2 m ²	

- Charge-sustaining



Simulation, cont.

- RTCS was compared to baseline parallel electric assist
 - Baseline optimized over city-highway
- These ADVISOR runs with RTCS showed a heavy reliance of operating point on NO_x emissions
 - Baseline steady state map from transient tests
 - Diesel engine used
 - Currently have a temperature correction factor of 8X cold-to-hot for NO_x emissions
 - Enhanced emissions modeling in ADVISOR is ongoing

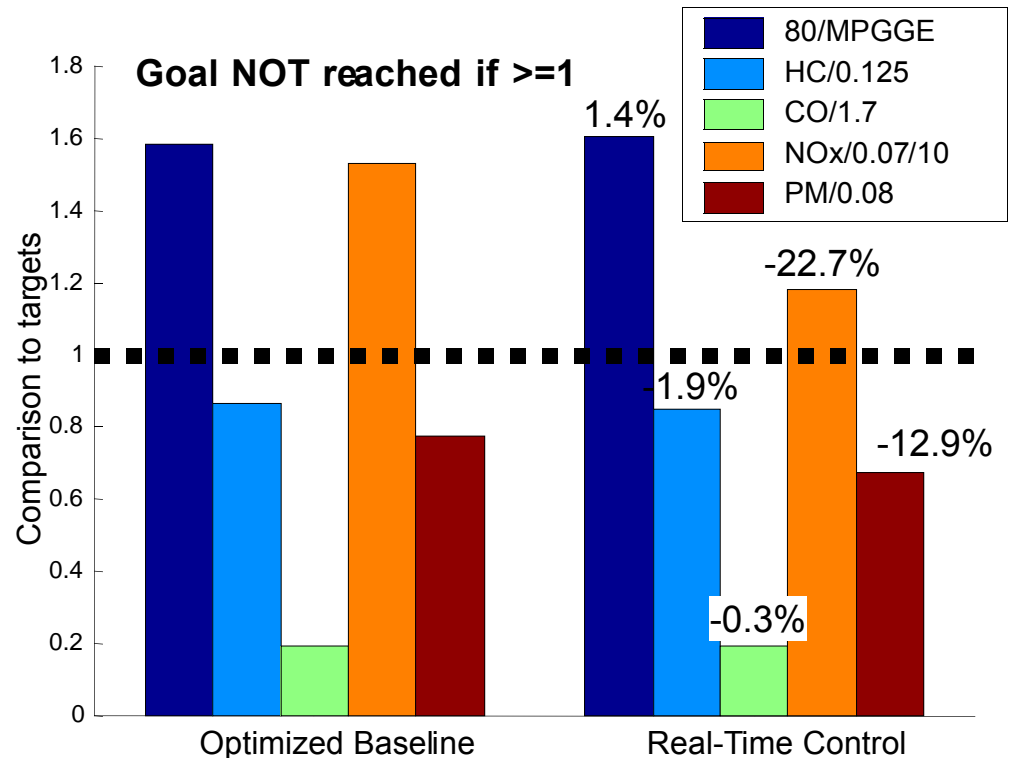




Results: Optimized Baseline and RTCS vs. Targets

■ FTP cycle

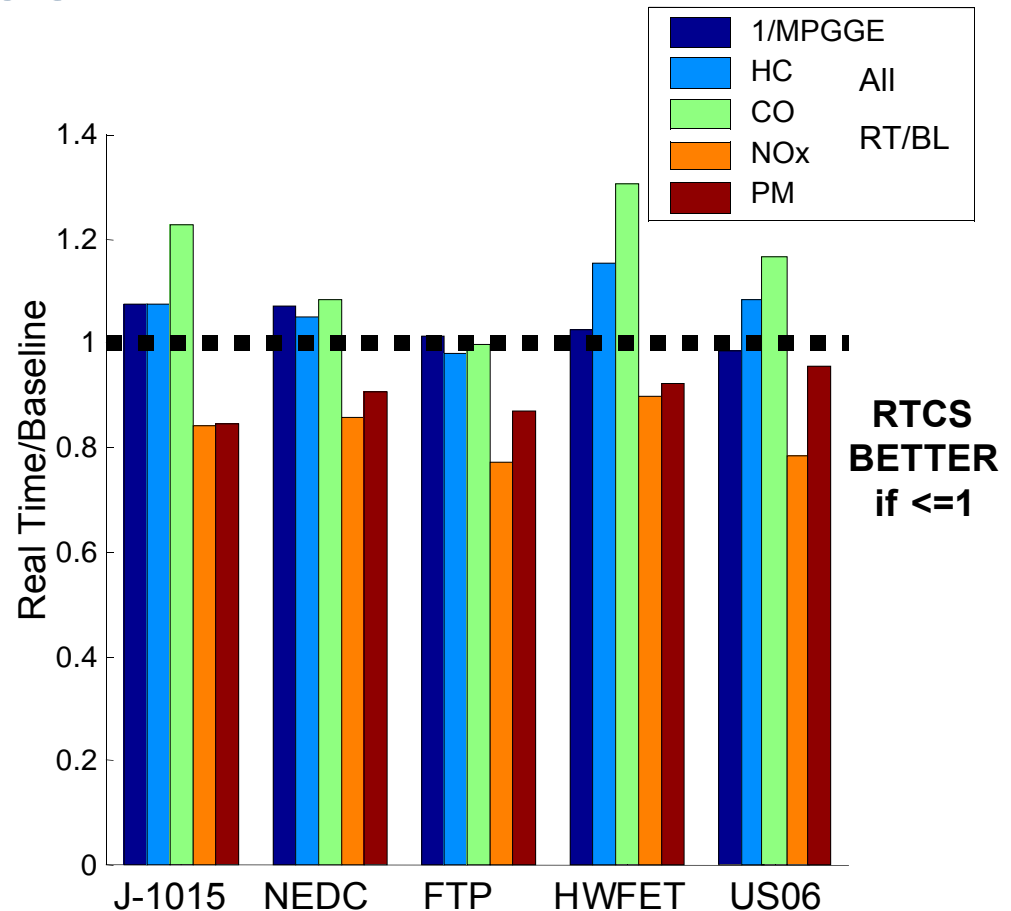
- Energy consumption increased 1.4%
- NOx dropped 22.7%
- PM dropped 12.9%
- HC dropped 1.9%
- CO dropped 0.3%





Results: Baseline vs. RTCS over multiple cycles

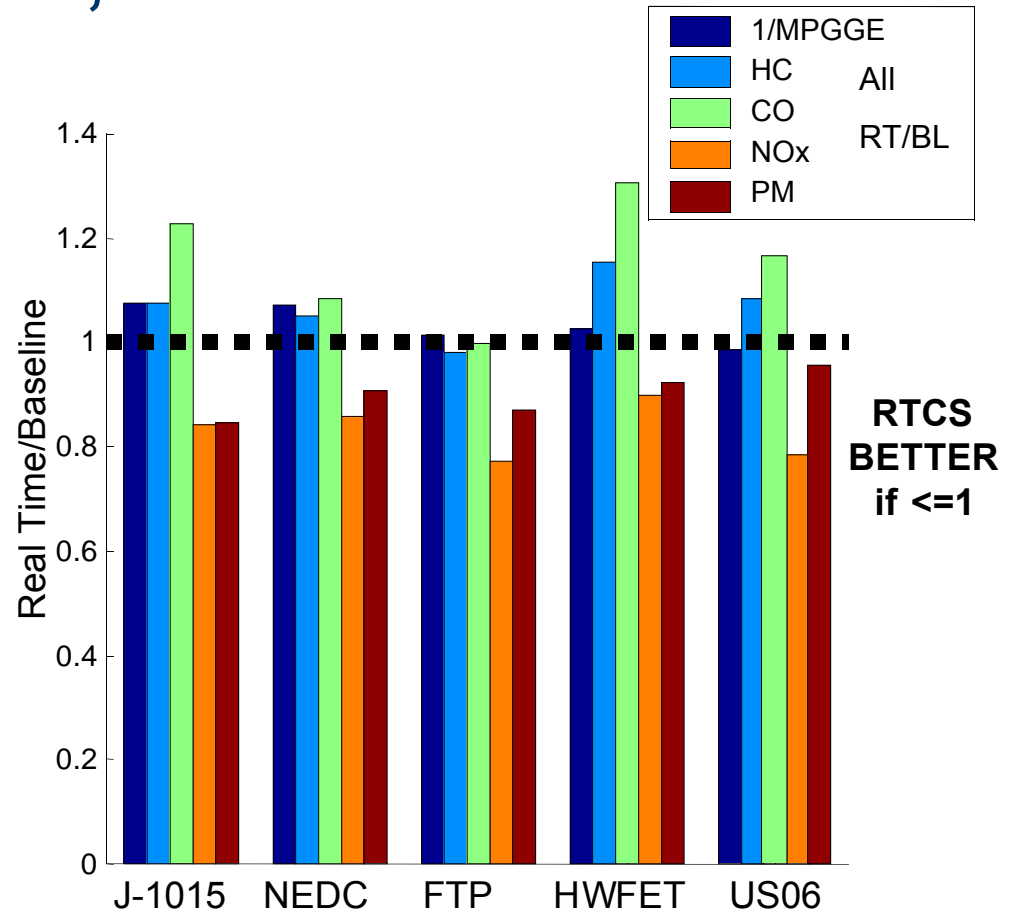
- NOx and PM significantly lower than baseline
 - 17% NOx and 10% PM on average
- Sacrifice of an increase in energy consumption
 - 3.4% average
- HC and CO emissions allowed to increase
 - remained below targets





Results: Baseline vs. RTCS over multiple cycles, cont.

- Flexibility to adjust to drive cycles
- Optimize on the fly

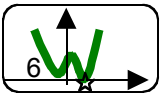
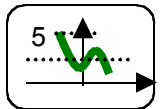
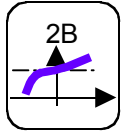




Summary of RTCS

■ RTCS Concepts

- Value of battery charge quantified based on the equivalent amount of fuel to replace that battery energy
- Relative importance of fuel economy and emissions through weightings.
- Overall impact function predicts instantaneous cycle performance (mpg, gpm) and combines five goals into one goal



■ RTCS Flexibility

- User-selectable targets
- Real-time adjustment to driving cycles based on expected free regenerative braking energy
- Incorporation of temperature effects on fuel use, engine-out emissions, and catalyst behavior





Conclusions and Future Work

■ RTCS Advantages

- Significant **NOx and PM emissions benefits** over the optimized static control strategy for the FTP cycle (**23%** and **13%** drop) at the price of a slight drop in fuel economy
- Better emissions performance over a range of drive cycles, coupled with comparable energy consumption
- Smaller **variation** in fuel economy over a range of cycles (Baseline: **29%** down to RTCS: **16%**)

■ Future Work

- Include RTCS in ADVISOR public release
- Further RTCS development
 - Emissions penalty of battery energy
 - Shifting strategies



The End

- Paper and ADVISOR at www.ctts.nrel.gov/analysis
- Questions